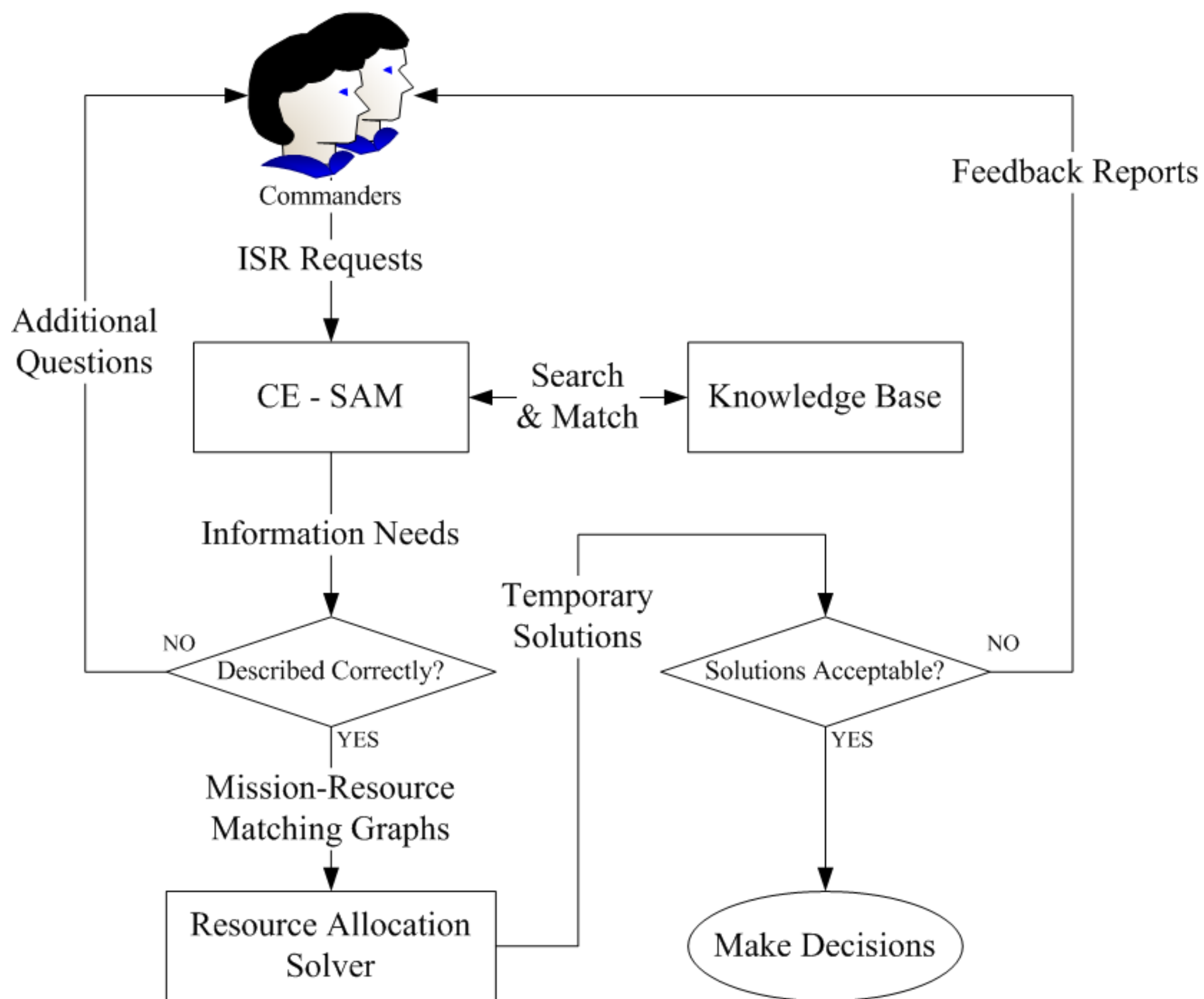


## Framework & Work Flows



## Stochastic Resource Allocation

**Needs of resources and achievable profits are assumed to change overtime:**

- Missions may execute longer/shorter than expected and consume more/less resources
- Missions may achieve either full or no profit in cases of different conditions

**Tunable thresholds are introduced for different criteria:**

- $p$ , as an overflow rate to set the maximum allowable probability on capacity constraint violation
- $q$ , as a confidence level to guarantee a lower bound of achievable profit

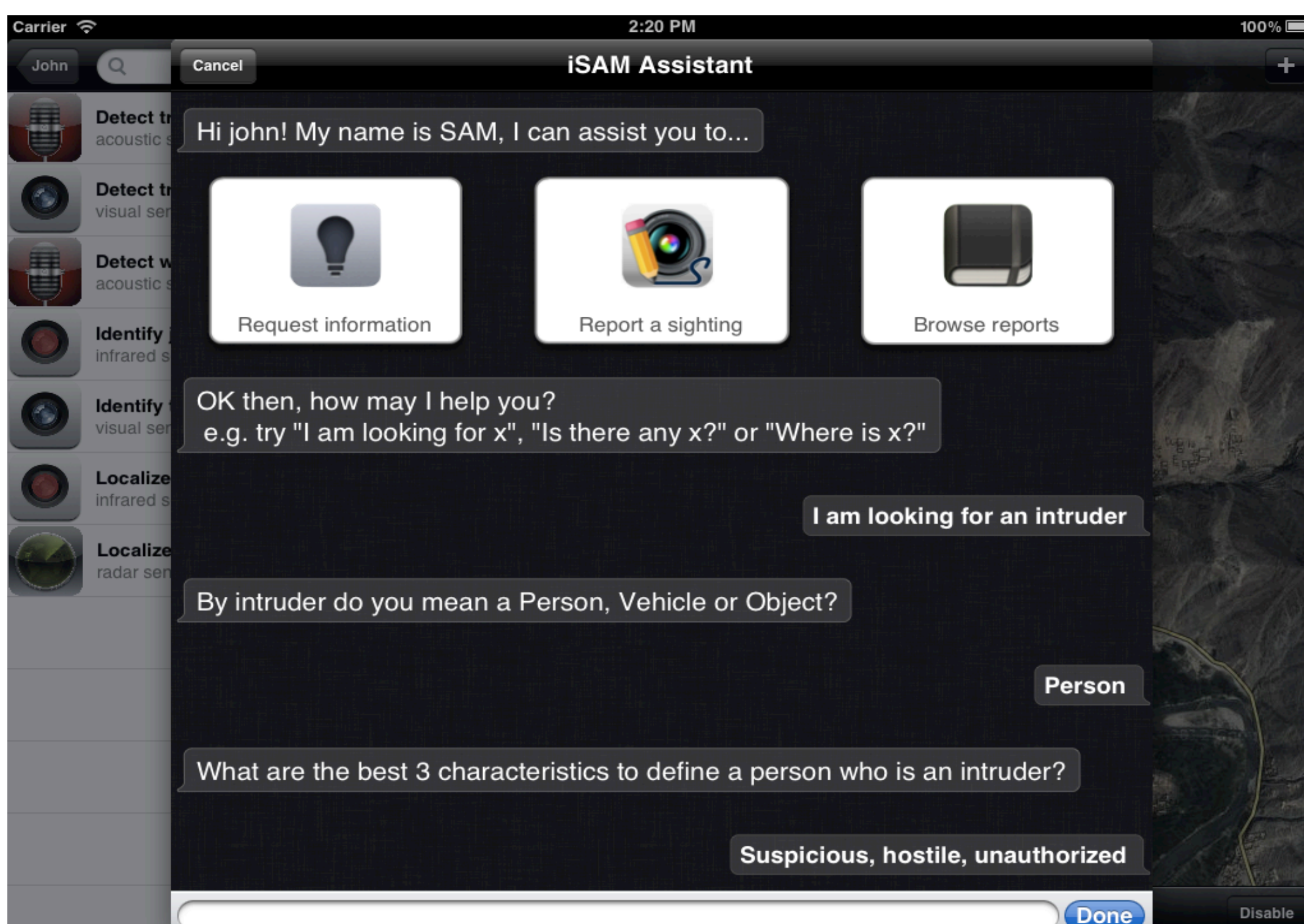
**The problem can be formulated as:**

$$\begin{aligned} \max \quad & \lambda \\ \text{s.t.} \quad & \Pr(\sum Needs > Capacity) < p \\ & \Pr(\sum Profits \geq \lambda) \geq q \end{aligned}$$

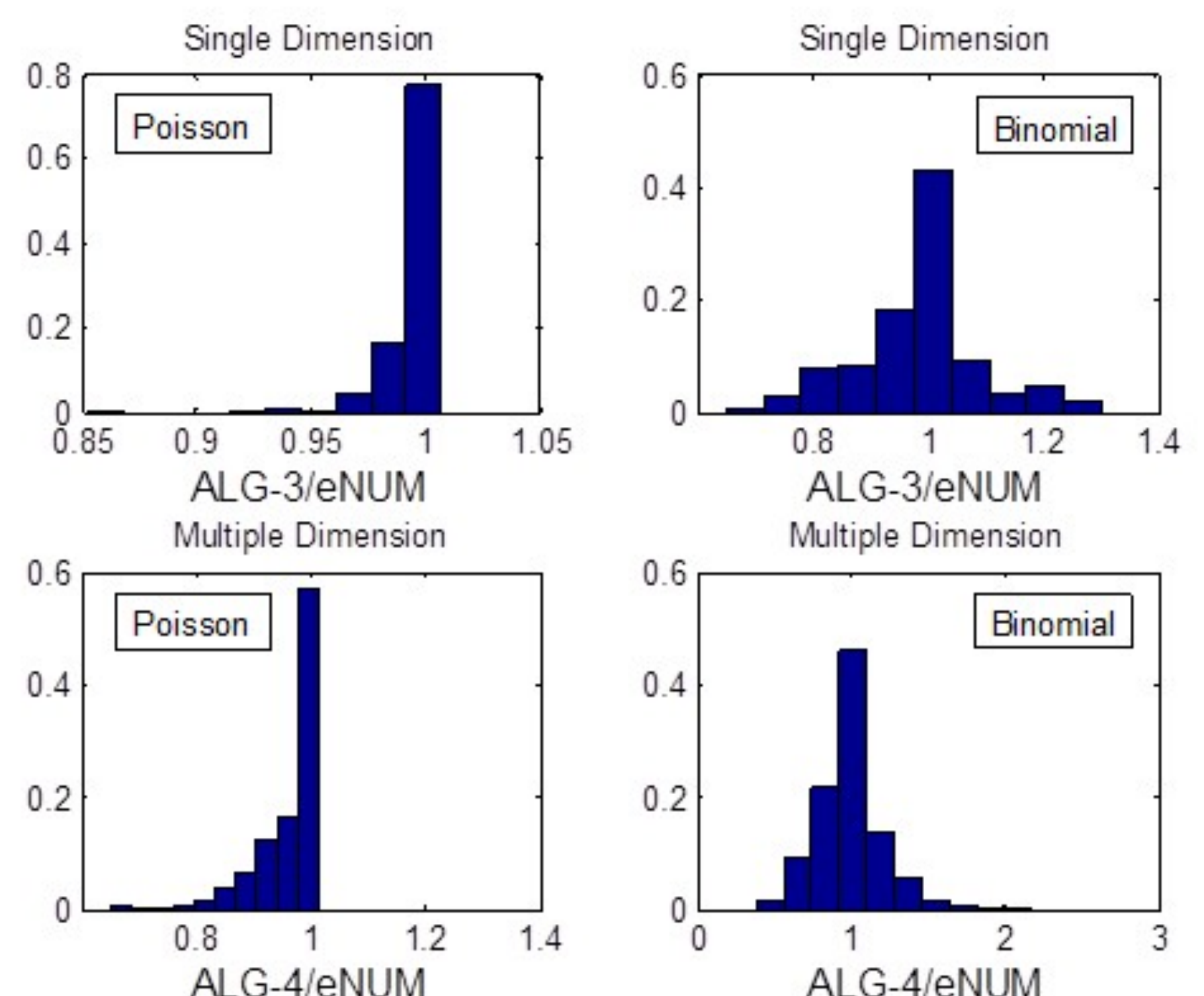
## Human-Machine Interaction

**CE-SAM (Controlled English Sensor Assignment to Missions)**, as a new interactive interface, is developed to guide the commanders to:

- Build a knowledge base of resource utilities
- Find proper bundles of resources to meet their needs
- Understand current conditions and refine missions



**Some experiment results are shown below:**



## Related Publications

- N. Hu et al., “*Resource Allocation with Non-Deterministic demands and profits*”, MASS 2013
- N. Hu et al., “*A System Architecture for Decision-Making Support on ISR Missions with Stochastic Needs and Profit*”, Proceedings of SPIE 2013